

Unveil the unseen: Using LiDAR to capture time-lag dynamics in the herbaceous layer of European temperate forests

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Complete List of Authors:	Lenoir, Jonathan; CNRS Delegation Nord Pas-de-Calais et Picardie, Unité de Recherche "Ecologie et Dynamique des Systèmes Anthropisés" EDYSAN, UMR CNRS 7058 Gril, Eva; CNRS Delegation Nord Pas-de-Calais et Picardie, Unité de Recherche "Ecologie et Dynamique des Systèmes Anthropisés" EDYSAN, UMR CNRS 7058 Durrieu, Sylvie; TETIS Horen, Hélène; UPJV, Unité de Recherche "Ecologie et Dynamique des Systèmes Anthropisés" EDYSAN, UMR CNRS 7058 Laslier, Marianne; UPJV, Unité de Recherche "Ecologie et Dynamique des Systèmes Anthropisés" EDYSAN, UMR CNRS 7058 Lembrechts, Jonas; University of Antwerp, Biology Zellweger, Florian; WSL Alleaume, Samuel; TETIS Brasseur, Boris; UPJV, Unité de Recherche "Ecologie et Dynamique des Systèmes Anthropisés" EDYSAN, UMR CNRS 7058 Buridant, Jérôme; UPJV, Unité de Recherche "Ecologie et Dynamique des Systèmes Anthropisés" EDYSAN, UMR CNRS 7058 Buridant, Jérôme; UPJV, Unité de Recherche "Ecologie et Dynamique des Systèmes Anthropisés" EDYSAN, UMR CNRS 7058 Dayal, Karun; TETIS De Frenne, Pieter; Ghent University, Forest & Nature Lab; Ghent University, Plant Production Gallet-Moron, Emilie; UPJV, Unité de Recherche "Ecologie et Dynamique des Systèmes Anthropisés" EDYSAN, UMR CNRS 7058 Marrec, Ronan; UPJV, Unité de Recherche "Ecologie et Dynamique des Systèmes Anthropisés" EDYSAN, UMR CNRS 7058 Marrec, Ronan; UPJV, Unité de Recherche "Ecologie et Dynamique des Systèmes Anthropisés" EDYSAN, UMR CNRS 7058 Marrec, Ronan; UPJV, Unité de Recherche "Ecologie et Dynamique des Systèmes Anthropisés" EDYSAN, UMR CNRS 7058 Marrec, Ronan; UPJV, Unité de Recherche "Ecologie et Dynamique des Systèmes Anthropisés" EDYSAN, UMR CNRS 7058 Meeussen, Camille; Ghent University Faculty of Bioscience Engineering, Department of Environment Rocchini, Duccio; Fondazione Edmund Mach, Biodiversity and Molecular Ecology Department, Research and Innovation Centre Van Meerbeek, Koenraad; KU Leuven, Department of Earth and Environmental Sciences Decocq, Guillaume; UPJV, Unité de Recherche "Ecologie et Dynamique des Systèmes
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2 Unveil the unseen: Using LiDAR to capture time-lag dynamics in the

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4 Preliminary author list

- 5 Jonathan Lenoir¹, Eva Gril¹, Sylvie Durrieu², Hélène Horen¹, Marianne Laslier¹, Jonas Lembrechts³,
- 6 Florian Zellweger⁴, Samuel Alleaume², Boris Brasseur¹, Jérôme Buridant¹, Karun Dayal², Pieter De
- 7 Frenne⁵, Emilie Gallet-Moron¹, Ronan Marrec¹, Camille Meeussen⁵, Duccio Rocchini^{6,7}, Koenraad
- 8 Van Meerbeek⁸, Guillaume Decocq¹

9 Affiliations

- 10 ¹Ecologie et Dynamique des Systèmes Anthropisés (EDYSAN, UMR 7058 CNRS), Université de Picardie Jules Verne, 1
- 11 rue des Louvels, 80000 Amiens, France
- 12 ²UMR TETIS, Univ Montpellier, AgroParisTech, CIRAD, CNRS, INRAE, Montpellier, France
- 13 ³Centre of Excellence on Plants and Ecosystems, University of Antwerp, Belgium
- 14 ⁴Institut fédéral de recherches sur la forêt, la neige et le paysage WSL, Zürcherstrasse 111, 8903 Birmensdorf, Suisse
- 15 ⁵Forest & Nature Lab, Ghent University, Geraardsbergsesteenweg 267, 9000 Gent, Belgium
- 16 ⁶BIOME Lab, Department of Biological, Geological and Environmental Sciences, Alma Mater Studiorum University of
- 17 Bologna, via Irnerio 42, 40126, Bologna, Italy
- 18 ⁷Czech University of Life Sciences Prague, Faculty of Environmental Sciences, Department of Spatial Sciences, Kamýcka
- 19 129, Praha-Suchdol, 16500, Czech Republic
- 20 ⁸Department of Earth and Environmental Sciences, Division Forest, Nature and Landscape, KU Leuven, Belgium

21 Abstract

22	1.	To understand time-lag dynamics in the response of biodiversity to macro-environmental
23		changes (e.g., macroclimate warming and atmospheric pollution), we need to consider
24		other anthropogenic forcing factors such as land-use changes and changes in management
25		practices that can have both compounding and confounding effects. This is especially true
26		in European temperate forests, where legacies from past human activities have left strong
27		imprints on today's understory plant species composition, generating long-term lagging
28		effects which can be mistakenly attributed to more recent macro-environmental changes.
29	2.	By combining the expertise of plant, soil, and historical ecologists together with remote
30		sensing scientists, we review the potential of light detection and ranging (LiDAR) to unveil
31		ghosts from the past in terms of former land uses and management practices.
32	3.	We show that imprints from past land uses and management practices can still be captured
33		today throughout well-chosen LiDAR-derived variables describing, at sub-decimetre scale,
34		the vertical and horizontal micro-variations of vegetation and terrain structure hidden
35		below treetops.
36	4.	Synthesis. We encourage plant and soil ecologists to use LiDAR data and to work with
37		historians, archaeologists, and remote sensing scientists in order to select meaningful
38		LiDAR-derived variables to account for time-lagged biotic responses to long-term macro-
39		environmental changes.
40	Кеуwс	ords
41	Archae	eology, biodiversity, climate change, climatic debt, disequilibrium dynamics, forest
42	manag	ement, historical ecology, legacy effects, microclimate, nitrogen deposition, remote
43	sensin	g, understory layer

44 "When light encounters a strong magical field it loses all sense of urgency. It slows right down." –

The current warming of the climate system is unprecedented in terms of its speed and spatial

45 Terry Pratchett, The Light Fantastic (1986)

46 Introduction

47

48 extent within the context of the past 2,000 years (Neukom et al., 2019), leading to important 49 regional, continental, and global biodiversity changes: species range shifts (Lenoir et al., 2020); 50 shifts in the phenological synchrony of species interactions (Kharouba et al., 2018); community thermophilization (i.e., increasing dominance of warm-adapted species) (Gottfried et al., 2012); 51 52 biotic homogenization (Staude et al., 2020); and even species extinction (Panetta et al., 2018). Yet, the velocity at which these biotic responses happen is generally lower than the velocity at which 53 54 the macroclimate is warming (Bertrand et al., 2011; Dullinger et al., 2012; Rumpf et al., 2019; Vitasse et al., 2021), leading to disequilibrium or lagging dynamics (Alexander et al., 2018; 55 Svenning & Sandel, 2013) sometimes also referred as the (macro)climatic debt in the scientific 56 57 literature (Bertrand et al., 2016; Devictor et al., 2012; Richard et al., 2021). Likewise, delayed 58 recovery of plant species richness and composition in response to the decreased inputs of atmospheric pollutants, after the peak in Europe during the 1970s for sulphur and during the 59 1980s for nitrogen, have been reported for both forest and grassland habitats (Riofrío-Dillon et al., 60 61 2012; Storkey et al., 2015). 62 Lagging dynamics in response to macroclimate warming and the reduction in atmospheric deposition, among other macro-environmental change drivers, are especially pronounced within 63 the herbaceous layer of temperate deciduous forests (Bertrand et al., 2011, 2016; De Frenne et al., 64 2013; Richard et al., 2021; Riofrío-Dillon et al., 2012; van Dobben & de Vries, 2017), which is the 65 most biodiversity-rich vegetation layer in these ecosystems (Gilliam, 2007; Landuyt et al., 2019). In 66 terms of biotic responses to macroclimate warming, thermophilization rates are ranging from 0.01 67

68	to 0.05°C per decade within understory plant communities of temperate forests, which is several
69	orders of magnitude lower (cf. greater lags) than the rates observed in other groups such as trees
70	(0.11°C per decade), bumblebees (0.14°C per decade), freshwater invertebrates (up to 0.22°C per
71	decade), or marine fishes and invertebrates (up to 0.38°C per decade) (see Table S5 in Richard et
72	al. (2021), and references therein, for a more exhaustive description). For comparative purposes,
73	mean annual temperature increased at a rate of 0.23°C per decade between 1995 and 2015 in
74	France (Richard et al., 2021). As for the recovery time following the reduction in atmospheric
75	deposition in Europe, lagging effects seem also more pronounced in the herbaceous layer of
76	forests than in grassland communities (Schmitz et al., 2019; Storkey et al., 2015; van Dobben & de
77	Vries, 2017). However, whether or not the magnitude of these time-lagged biotic responses in
78	temperate forests can be attributed solely to macroclimatic warming or atmospheric deposition
79	remains an open question. To resolve this, it is of utmost importance to also consider other
80	anthropogenic forcing factors such as past land-use changes and historical changes in forest
81	management practices that can have both compounding and confounding effects with other more
82	recent environmental change drivers (Forister et al., 2010; Guo et al., 2018; Larsen, 2012; Warren
83	et al., 2001). Indeed, the scientific literature is full of examples, detailed below, illustrating how
84	the history of forest management practices and land uses can interact, synergistically or
85	antagonistically, with either macroclimate warming or atmospheric deposition, to delay or
86	sometimes speedup changes in the understory of European temperate forests.
87	As macroclimate warming accelerates, it is assumed that mean annual temperatures below
88	treetops increase as well but at lower rates than outside forests due to the lower coupling
89	between macroclimate and microclimate inside the forest understory (Lenoir et al., 2017).
90	Accordingly, De Lombaerde et al. (2021) predicted that maximum temperatures will, on average
91	for the 2060-2080 period, warm less inside (+0.27°C) than outside (+0.60°C) forests if the local
92	forest cover is maintained. However, maximum temperatures may also warm faster inside the
52	4

93	forest understory than outside if canopy cover is reduced due to, for instance, management
94	interventions or forest dieback related to drought and pest damages. Such forest microclimate
95	dynamics driven by changes in canopy cover could explain part of what seems to be a delayed
96	biotic response to macroclimate warming, meaning that the so-called macroclimatic debt involves
97	microclimatic processes (De Frenne et al., 2021; Zellweger et al., 2020). Accordingly, Richard et al.
98	(2021) have recently demonstrated that lags in community thermophilization are accumulating
99	over time in the herbaceous layer of denser and older forest stands in France, while anthropogenic
100	and natural disturbances generating canopy gaps above the herbaceous layer tended to reduce
101	these lags. Hence, stand characteristics are important determinants of time-lag dynamics
102	observed in the herbaceous layer of temperate forests in response to macroclimate warming
103	(Brice et al., 2019; Richard et al., 2021). Besides, changes in stand characteristics over time interact
104	with long-term environmental changes through complex historical trajectories of forest
105	management practices and natural disturbances (e.g., fire, drought, wind storm). For instance, in
106	Europe, Perring et al. (2018) have shown that the trajectories of changes in forest plant
107	community composition over 40 years were clearly influenced by complex interactions between
108	management legacies from over 200 years ago and long-term environmental changes, in terms of
109	both the rate of nitrogen deposition and the rate of temperature change.
110	Time-lagged biotic responses that we attribute today to macroclimatic warming or to the
111	reduction in atmospheric deposition may also involve other long-term processes, such as legacy
442	

effects of soil compaction due to mechanized timber harvesting as well as more ancient legacy

effects of past land uses (Bürgi et al., 2017), operating through microclimate and soil memory

effects. For instance, it has been recently demonstrated that old skid trails left by forestry vehicles

more than 50 years ago locally increase soil compaction and alter microclimatic conditions in the

- soil (humidity and temperature), which leaves a strong imprint on contemporary community
- 117 composition and diversity in the herbaceous layer of temperate forests (Wei et al., 2015). More

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precisely, by limiting water infiltration, skid trails locally increase the proportion of wetland plant species in the community (Buckley et al., 2003), which alters community composition such that the community may not only indicate wetter but also cooler conditions over time when analysed through the lens of thermophilization indices solely. Indeed, a cooling effect is usually concomitant with the humidifying effect of vegetation (Zhang et al., 2013). In such a case, time-lagged biotic responses to soil compaction by skid trail may be mistakenly attributed to an inflated macroclimatic debt.

125 The field of historical ecology (Szabó, 2015) is full of examples showing that current local biodiversity continues to be influenced by past management practices and land uses, including fire 126 127 regimes, through complex biotic lags usually involving long-lasting effects of changes (or absence 128 of changes) in landscape configuration and soil abiotic conditions (Dambrine et al., 2007; Dupouey et al., 2002; Jung et al., 2019; Metzger et al., 2009). For instance, time since afforestation, and thus 129 130 land-use history, has left a strong imprint on the herbaceous layer of temperate deciduous forests in Europe, with several forest plant species (i.e., forest specialists) clearly associated with ancient 131 forests (land continuously forested for several centuries) (Rackham, 2008) as opposed to more 132 133 recent forests (Hermy et al., 1999; Peterken & Game, 1984; Valdés et al., 2015; Verheyen et al., 134 2003). Similarly, historical landscape connectivity can strongly affect the present distribution pattern of herbaceous forest plants in fragmented forests and hedgerows through changes in 135 136 habitat configuration and composition (Lenoir et al., 2021; Lindborg & Eriksson, 2004; Metzger et al., 2009). Perhaps more surprisingly, former Roman agricultural practices throughout Europe can 137 still have irreversible impacts on forest biogeochemical cycles and biodiversity by increasing 138 139 today's soil pH, available phosphorus and nitrogen, and consequently the frequency of nitrogen-140 demanding species (Dambrine et al., 2007; Plue et al., 2008; Vanwalleghem et al., 2004). In such a case, without considering historical information on past land uses, one may mistakenly interpret 141 todays' occurrence of nitrogen-demanding species in the community as a response to the high 142

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143	nitrogen deposition during the 1980s while part of it may actually be due to longer-term lagging
144	effects induced by former Roman agricultural practices. By looking at terrain morphology and
145	micro-topographic variations in today's landscapes, archaeologists and geo-historians can read
146	such long-term legacies from past land uses, unearth artefacts of former human occupations, and
147	provide invaluable information to explain current biodiversity patterns (Briggs et al., 2006; Closset-
148	Kopp & Decocq, 2015; Dambrine et al., 2007; Dupouey et al., 2002; Plue et al., 2008). Hence, to
149	decipher the main determinants of time-lag dynamics in the herbaceous layer of temperate
150	forests it is necessary to analyse the response of species population and community dynamics to
151	contemporary macro-environmental changes (e.g., macroclimate warming or nitrogen deposition)
152	in the light of historical management practices and past land uses.
153	Vertical and horizontal micro-variations at sub-decimetre scale in both vegetation and terrain
154	structure can bear the imprints of historical management practices and land-use legacies which
155	are still contributing to today's biodiversity, and thus to time-lagged biotic responses to macro-
156	environmental changes, by locally altering microclimatic conditions near the soil surface as well as
157	edaphic conditions (Fig. 1). Light detection and ranging (LiDAR) data (Box 1) can capture these
158	vertical and horizontal micro-variations (i.e., structural traits) below treetops (Fig. 2). Indeed,
159	LiDAR data can provide quantitative metrics of both stand characteristics and micro-topographic
160	variations below the canopy at unprecedented detail, often impossible to perceive for the human
161	eye or to describe with traditional field measurement methods (Chase et al., 2012; Dassot et al.,
162	2011). To illustrate this, we first put on our plant-ecologist hat to show how LiDAR data can
163	capture detailed stand characteristics to unveil recent but also historical forest management
164	practices that affect current forest microclimates and thus the time-lag dynamics of understory
165	plants' responses to long-term environmental changes. Then, we put on our soil-ecologist hat to
166	illustrate how LiDAR data can unveil the imprints of former skid trails left by forestry vehicles that
167	are still affecting current plant community composition through soil compaction. Third, we take a

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168	historical-ecologist viewpoint to demonstrate how LiDAR data can unveil long-term land use
169	history that may still affect contemporary plant community composition in the herbaceous layer.
170	Finally, we discuss research perspectives in light of the most recent advances in LiDAR technology
171	and its combination with other remote sensing technologies as well as with recent developments
172	in computer science. We conclude that LiDAR can be used as a tool to boost trans-disciplinary
173	research between plant ecologists, foresters, soil ecologists, archaeologists, historical ecologists,
174	and remote sensing scientists to advance our knowledge of time lags in the response of
175	understory plant communities to long-term macro-environmental changes.

176 **Box 1: LiDAR principles**

177 Measurement principles

178 Light detection and ranging (LiDAR) is an active remote-sensing technology based on emissionreception of a laser beam. LiDAR can be divided into two main categories (Durrieu et al., 2015; 179 Grotti et al., 2020): (1) time-of-flight LiDAR (Fig. 2) assessing distances by measuring the roundtrip 180 181 time for a short laser pulse, in general emitted by a near-infrared or visible (green) laser, to travel between the sensor and a target; versus (2) phase-shift LiDAR emitting a continuous wave laser 182 with intensity modulated at a series of frequencies to determine distances through shifts in phase 183 184 of the returned modulations. Phase-shift LiDAR have higher measurement rates and can thus collect data at a much faster speed than time-of-flight LiDAR. They also measure distance with a 185 precision of up to few millimetres against few centimetres for time-of-flight LiDAR. However, their 186 187 maximum measurement range is much shorter, which makes phase-shift LiDAR more adapted for terrestrial LiDAR systems (TLS) than for airborne LiDAR systems (ALS) (Fig. 2). Additionally, phase-188 shift LiDAR is more prone to artefacts, for example those caused by range averaging, when a beam 189 190 partially intercepts more than one object.

191 Scanning and geolocating principles

192 In order to acquire LiDAR data across a given area or landscape, a scanning system is used to 193 deflect the emitted laser beams in different directions throughout the target scenery (Fig. 2). This 194 is achieved thanks to: (1) the combination of a moving (e.g., rotating) mirror and the movement of either the scan head for static TLS or the vehicle on which the LiDAR is embedded for non-195 stationary systems like ALS (Tan et al., 2018); and (2) the multiplication of standpoints for TLS or 196 197 flight lines for ALS. When both the scanning angles and the position of the LiDAR in a geographic 198 reference system are known at the time of range measurements, the absolute position of the targets on the Earth's surface can be inferred. For mobile ALS, real-time sensor position and 199

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200	orientation are obtained thanks to a differential global navigation satellite system (DGNSS) and an
201	inertial measurement unit on-board the platform. For static TLS, point cloud geolocation can be
202	achieved by measuring either scan positions or the positions of a set of high reflective targets
203	distributed in the field, which are clearly identifiable in the point clouds and used for the merging
204	of several scans. Positions can again be measured using a DGNSS. To improve location accuracy in
205	forest environments, it is recommended to use a DGNSS in a neighbouring open area as well or
206	coupled with a total station (cf. tacheometer).
207	Spatial distribution of LiDAR measurements and occlusions
208	The spatial distribution of LiDAR measurements results from the combination of several factors,
209	such as laser emission rate, scanning system, and vector velocity for non-stationary ALS. However,
210	a major phenomenon impacts the spatial distribution of LiDAR measurements in forested
211	environments: occlusions. Like natural light, laser beams can penetrate through vegetation
212	openings but, when intercepted by vegetation elements, it is mostly reflected or absorbed,
213	generating shadows or occluded areas behind these elements (e.g., foliage, stems, flowers).
214	Besides, the quantity of light continuing its path through vegetation decreases each time part of a
215	laser beam hits a vegetation element. As a result, vegetation sampling is getting sparser when the
216	laser beam goes deeper inside the vegetation (Fig. 2). For TLS, point density decreases with the
217	distance from scan positions below the canopy, leading to sparser point clouds towards the top of
218	the canopy and generating occlusion areas behind large tree trunks located very close to the
219	scanning position. For ALS, the understory vegetation and the ground surface, including deadwood
220	and litter lying on the ground, are less densely measured than the top of the canopy, especially
221	after leaf-out and tree canopy closure in temperate deciduous forests.

222 Using LiDAR-derived metrics of vegetation structure to capture time-lag dynamics in the

223 response of herbaceous plant communities to long-term environmental changes

224 Forest structure is acknowledged to be a key factor to explain current plant species diversity and 225 community composition in the understory (Oettel & Lapin, 2021; Walter et al., 2021). LiDAR technology allows the description of complex aspects of the forest structure that are 226 complementary to those observed by foresters during field surveys (Box 2) (Bouvier et al., 2015; 227 Venier et al., 2019). Primarily underpinned by objectives of forest resource inventory and 228 229 management, the capacity to remotely assess stand characteristics such as basal area, stem density, dominant height, wood volume, and biomass distribution, has been widely studied and is 230 231 operationalized in a variety of forest contexts (Moeslund et al., 2019; White et al., 2016; Wulder et 232 al., 2013). Among those descriptors of stand attributes routinely used by foresters to assess forest resources, some, like stand structure (e.g., basal area, diameter diversity, tree height), 233 234 management intensity, and tree species composition have proven to be useful to model current plant diversity in the forest understory (Oettel & Lapin, 2021; Wei et al., 2020). However, many 235 other complementary metrics (e.g., canopy volume, vertical leaf density profile, understory shrub 236 237 cover), not routinely used by foresters to assess vegetation structure because they are difficult to 238 measure in the field, can be derived from LiDAR data (Fig. 3). In this review, we argue that LiDAR data can be used to derive variables describing the complexity of the vertical layering of 239 240 vegetation in temperate forests, including subtle vertical structures bearing the imprints of extreme weather conditions as well as the memory of past forest management practices for which 241 we have good records in Europe. 242

It is widely acknowledged that historical forest management practices, such as coppicing which
was widespread in European temperate forests before World War II (WWII), are major drivers of
current plant community composition and distribution in the forest understory (Bartha et al.,

246	2008; Becker et al., 2017a; Bricca et al., 2020; Decocq et al., 2004; Della Longa et al., 2020;
247	Müllerová et al., 2015). For instance, former coppice-with-standards (CWS) have left a visible
248	signature on current stand structure as well as on current plant species composition in the
249	herbaceous layer, even after conversion to high forests (HF), a very common practice in Europe
250	after WWII. Importantly, these changes in forest management practices in Europe happened
251	somewhat concomitantly with climate change and increased inputs of nitrogen via atmospheric
252	deposition, leading to complex compounding and confounding effects on the observed changes in
253	plant species composition in the herbaceous layer (Becker et al., 2017b; Perring et al., 2018).
254	Traditionally, CWS were managed as multi-storied stands consisting of a matrix of even-aged
255	stems (coppice) in the lower storey – cut down for firewood production in short rotations – and
256	single-stem (emergent) trees (i.e., standards) in the upper storey – left standing during longer
257	rotations for timber production. Whether or not CWS casts more shade at the forest floor than HF
258	remains unclear, but conversion from CWS to HF implies more regular thinning operations over
259	time, potentially leading to more frequent light pulses enhancing microclimate warming and
260	community thermophilization in the understory, ultimately compounding and confounding the
261	impact of macroclimate warming on understory plant communities (Zellweger et al., 2020).
262	Changing socio-economic conditions throughout history have also led to the complete
263	abandonment of active timber management in some regions of Europe (see Perring et al., 2018),
264	generating prolonged absence of high light conditions in the forest understory. Such trajectories
265	may have led to a loss of light-demanding plant species from open habitats and an increase of
266	typical shade-tolerant plant species (i.e., forest specialists) (Baeten et al., 2009), reducing
267	community thermophilization and contributing to the lagging response of understory forest plant
268	to macroclimate warming (Richard et al., 2021).

269 Using LiDAR technology to scan the vertical layering of vegetation and better capture the

270 understory structure hidden below treetops (**Box 2**), as a mean to identify the complex trajectories

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271	outlined above, holds untapped potential to understand time-lag dynamics that depends upon
272	past management legacies (Perring et al., 2018). For instance, a set of airborne LiDAR-derived
273	variables describing the vertical distribution of canopy height and cover was successfully applied
274	to identify old coppices in a Mediterranean context (Bottalico et al., 2014). The most
275	straightforward metrics to describe the vertical structure of vegetation within a given spatial grid
276	cell include the mean and standard deviation of height values above the ground surface for all the
277	points classified as vegetation and belonging to the focal grid cell. Yet, these raw summary
278	statistics aggregated in a 2D pixelated space may not fully capture the complex layering of
279	vegetation in the understory (see Box 2). Refined approaches to assess the effective number of
280	vegetation layers below treetops consist in computing height percentiles and the number of
281	echoes or point density at several heights (Frey et al., 2016; Stickley & Fraterrigo, 2021). Using
282	airborne LiDAR data, Stickley & Fraterrigo (2021) summarized the vertical structure of temperate
283	deciduous forests in the Great Smoky Mountains National Park into five height classes and found
284	that variation in maximum temperature in the understory was best explained by the buffering
285	effects of the low-understory (below 5 m height) and low-canopy (from 10 to 15 m height) layers.
286	Finally, it is possible to compute more advanced LiDAR-derived metrics per unit of volume (see
287	Box 2) by relying on the resolution of the transmittance equation using the Beer-Lambert Law,
288	which relates the attenuation of light through a turbid medium – in this case, leaves and branches
289	- to the properties of that medium, or on the maximum likelihood theory (Soma et al., 2018). For
290	instance, plant area density (PAD) (in m ² m ⁻³) can first be computed for each single voxel, a 3D cell
291	unit, from the local transmittance values by applying Beer-Lambert's turbid medium
292	approximation (Vincent et al., 2017) (Fig. 3e). Thus, PAD values better reflect the amount of plant
293	material participating to light occlusion in the canopy than the above-mentioned metrics based on
294	point density. From vertical profiles of PAD values (Fig. 3f), it is then possible to summarize the
295	entire vertical structure of vegetation, including the understory, by computing the plant area index

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296	(PAI), which is the integral (area under the curve) of PAD profiles. Hence, PAI describes the entire
297	column of plant material participating to light occlusion and thus indirectly reflects the amount of
298	light reaching the forest floor. Figure 4 shows that a denser forest with a complex shrub layer and
299	thus a higher PAI value (e.g., PAI = 6.28) than a less vertically complex and more open forest (e.g.,
300	PAI = 4.72) provides a higher buffering capacity during spring and summer, reducing daily mean
301	temperature by more than 5°C (against 3°C for the open forest). It is also possible to compute PAI
302	within a restricted vegetation layer, such as the shrub layer (e.g., below 7 m). This way, it is
303	possible to partition PAI values among vegetation layers and focus on the additional insulating
304	effect provided by shrubs (Fig. 4), which may bear the imprints of historical management practices
305	contributing to time-lag dynamics in the herbaceous layer. Spatially contiguous maps of forest
306	microclimate predictions (e.g., Frey et al., 2016; George et al., 2015) integrating the buffering
307	effects of the understory shrub layer through the use of PAI values are especially promising as they
308	may reflect the complex trajectories of forest management changes, and explain time-lag
309	dynamics in the response of the herbaceous layer to long-term environmental changes (Richard et
310	al., 2021; Zellweger et al., 2020).

311	Box 2: The potential of LiDAR-derived variables to capture vertical structures in the understory
312	Traditional forest inventory methods to measure forest structure in the field cannot be easily
313	applied contiguously at fine spatial resolutions and across large spatial extents. Moreover,
314	traditional forest surveys cannot extract the accurate three-dimensional structure of forests,
315	including tree cover rate, gap distribution, and a detailed vertical description of the understory.
316	Using LiDAR data can help to overcome these limitations (Almeida et al., 2019) (Fig. 3). Once the
317	digital terrain model (DTM) (Fig. 3a) of a given area has been computed from the set of points
318	classified as "ground", it is possible to compute the exact height, relative to the ground surface, of
319	each point classified as "vegetation" across the area. This information can then be exploited to
320	extract very simple metrics of the vertical structure of vegetation, such as canopy density above a
321	specific height (Fig. 3b) or maximum canopy height (Fig. 3c). The level of details provided by LiDAR
322	data, and especially TLS data (Figs. 3d), to quantitatively describe the vertical layering of
323	vegetation in the understory of temperate forests (Fig. 3e,f) is unprecedented compared to
324	traditional field approaches (Venier et al., 2019). Foresters usually start recording and measuring
325	trees in the field above a minimum diameter at breast height (DHB) of 7.5 cm. Yet, individuals of
326	less than 7.5 cm DBH are also an important component of the understory shrub layer that can be
327	partly captured depending on the quality of the raw LiDAR point cloud. The quality not only
328	depends on the point density, which can be high in case of TLS data (Fig. 3d-f), but also on the
329	intensity of the return and the number of echoes registered. For ALS data, full-waveform laser
330	scanning allows to digitize the complete waveform of each backscattered pulse and extract more
331	small echoes – even during leaf-on conditions – that may hold key information on the structure of
332	the understory shrub layer. From the raw LiDAR point cloud, the most intuitive approach to
333	capture the understory shrub layer is to separate points classified as "vegetation" into different
334	vertical strata and extract summary statistics aggregated in a 2D pixelated space describing either

335	the mean, minimum, maximum, standard deviation, skewness, kurtosis, or relative percentage of
336	the distribution of the points within a vertical stratum (e.g., Frey et al., 2016; Stickley & Fraterrigo,
337	2021). To avoid using too many summary statistics for each vertical layer separately, LiDAR point
338	clouds classified as vegetation can also be aggregated in a 3D voxelated space to compute metrics
339	per unit of volume, like the 3D distribution of plant or leaf area density (PAD or LAD) (Fig. 3e). For
340	instance, Almeida et al. (2019) showed that LAD profiles have the capacity to track changes in
341	forest structure under different forest management practices. This biophysical information can be
342	further analysed to provide vertical vegetation profiles or information on gap size and distribution
343	(Fig. 3f). Vertical profiles and gap fraction together can better describe the 3D characteristics of
344	the forest. Venier et al. (2019) identified several metrics that are expected to directly capture
345	vegetation density in the understory: fractional cover (FRAC); plant or leaf area density (PAD or
346	LAD) profiles; voxel cover (VOX); and normalized cover (NORM). Additionally, the Gini coefficient is
347	a reliable descriptor of variation in tree sizes (Knox et al., 1989). Valbuena et al. (2016)
348	demonstrated the potential of LiDAR-derived estimations of the Gini coefficient to highlight
349	structural differences between forests that have been protected since the beginning of the 20th
350	century vs. forests presently under intense management.

351 Using LiDAR data to highlight soil compaction from skid trails affecting current biodiversity

352 patterns in the forest understory

Numerous studies have highlighted the long-lasting effects of heavy forestry vehicles on soil 353 354 processes and forest herb composition (Closset-Kopp et al., 2019; Godefroid & Koedam, 2004; Wei et al., 2015). These effects include: (i) diaspore dispersal via the mud attached to tires and wheels 355 (i.e., agestochory) and air displacement induced by the vehicle's movements, which facilitates 356 anemochory; (ii) the creation of microreliefs within, beside, and between wheel tracks, generating 357 358 a complex mosaic of microenvironments; and (iii) local changes in soil abiotic (e.g., porosity, 359 microclimate, chemistry) and biotic (e.g., microbial activity) conditions. In particular, soil 360 compaction and the formation of deep ruts on the soil surface often impede water infiltration, 361 oxygen supply, nutrient bioavailability, as well as root development (Arocena, 2000; Cambi et al., 2018; Kozlowski, 1999). This provides regeneration niches and suitable habitat conditions to a 362 363 range of (non-forest) plant species, such as aquatic weeds, sedges and rushes, as well as ferns (Closset-Kopp et al., 2019) but on the other hand can negatively affect recruitment of other 364 species (e.g., trees). These three processes can lead to an increase in local species richness, yet 365 also a process of homogenization among forest habitats, by facilitating the colonization of the 366 367 same suite of wetland and ruderal species (Closset-Kopp et al., 2019; Godefroid & Koedam, 2004; Kozlowski, 1999). 368

Ruts and soil compaction can be measured in the field, via rut depth, bulk density, or penetration resistance, but the methods are time consuming to apply across large areas. Recently, several studies highlighted the efficiency of remote sensing in the evaluation of rutting intensity and spatial distribution (Marra et al., 2018; Mohieddinne et al., 2019; Niemi et al., 2017). Some of them, using unmanned aerial vehicles equipped with digital cameras for high resolution photogrammetry, returned a fine description of rut density associated with forest harvesting

375	(Marra et al., 2018; Talbot et al., 2018). However, this approach is only applicable to recently clear-
376	cut areas. In contrast, LiDAR data offers an interesting alternative to map skid trails below treetops
377	(Fig. 5) (Koren et al., 2015; Mohieddinne et al., 2019; Niemi et al., 2017). Indeed, points classified
378	as "ground" in the LiDAR point cloud can be used to generate a digital terrain model (DTM) at sub-
379	decimetre resolution so as to detect microrelief variations due to skid trails. The most
380	straightforward approach to highlight skid trails from a DTM is to use local relief models (LRMs)
381	that are widely used in archaeology to capture local, small-scale elevation differences after
382	removing the large-scale landscape forms from the data (Hesse, 2010). While TLS data can yield
383	LRMs at a very high accuracy over limited spatial extents (Koren et al., 2015), ALS data allows
384	assessing the impact of skid trails over much larger areas in a spatially contiguous manner (Niemi
385	et al., 2017). Figure 5 clearly shows how ALS data can shed light on skid trails in the Compiegne
386	forest, a managed state forest in Northern France. The LRM reveals small-scale topographic
387	variations such as ruts, which sometimes appear as parallel paths following permanent skid trails
388	as delineated by forest managers (Fig. 5a, bottom panels) but also as numerous meandering paths
389	crossing each other (Fig. 5b, bottom panel). Yet, LRMs only highlight ruts resulting from the traffic
390	intensity without providing the means for an automatic detection of these linear small-scale
391	topographic elements in the landscape. Indeed, one still needs to digitize, manually, the
392	illuminated ruts in the LRM image in order to analyse these elements afterwards. By doing so
393	across the entire Compiegne forest, we found that the surface area covered by skid trails can
394	reach 40 to 80% in several of the forest management units. Noteworthy, in some of these units,
395	many ruts intersect (Fig. 5b). This suggests that either vehicles travel unevenly during a given
396	operation or that older ruts resulting from several successive forestry operations persist for a very
397	long time (at least 50 years) (Ebeling et al., 2016; Mohieddinne et al., 2019) with potential long-
398	lasting effects still visible on today's plant species composition and diversity in the herbaceous
399	layer (Wei et al., 2015). More specifically, the cumulated effect of soil compaction due to repeated

18 Journal of Ecology: Confidential Review copy 400 traffic of heavy forest harvesters and forwarders contribute to local increases in the proportion of wetland plant species in the community (Buckley et al., 2003) and to the homogenization of plant 401 communities in the forest understory (Closset-Kopp et al., 2019), most likely with a lagging effect. 402 403 Without considering skid trails, such time-lag dynamics can be misattributed to other concomitant drivers of change in environmental conditions, such as nitrogen deposition known for being also 404 responsible for the biotic homogenisation of understory plant communities (Staude et al., 2020). 405 406 Currently, the main challenge to account for the impact of skid trails on understory vegetation at large spatial extents is to automatize the detection of ruts from LRM images. More research is still 407 needed to achieve that but one possibility is to train a model with LRM data using machine 408 learning or deep learning algorithms such as convolutional neural networks (CNNs), which is 409 widely used in the field of computer vision (Ren et al., 2017). 410

Using LiDAR data to unveil past land uses affecting current biodiversity patterns in the forest

412 understory

One leading research question in historical ecology is (Plue et al., 2009): what did past human 413 societies leave behind and how does this influence present ecosystem functioning? For ecologists, 414 this question can be difficult to answer without a comprehensive knowledge of past interactions 415 between human societies and the environment at various spatial and temporal scales. LiDAR 416 technology has prompted an "archaeological revolution" by making it possible to identify, map, 417 418 and analyse hidden objects and structures (Costa et al., 2020; Hesse, 2010). In terms of historical ecology, this is especially true for forested lands, where traditional remote sensing techniques 419 such as aerial photography cannot unveil archaeological features hidden below treetops. In such 420 421 situations, ALS can help to spot thousands of artefacts in a much shorter time frame than the decades of pedestrian field surveys that would have been otherwise necessary to discover only the 422 423 most visible part of these artefacts (Chase et al., 2012; Štular et al., 2021). In many cases, ALS has revealed previously unrecorded archaeological features. Spectacular examples of unexpected 424 findings are the medieval landscape planning by the classical Khmer civilization at Angkor (Evans et 425 426 al., 2013) and the early Maya metropolises in Guatemala (Canuto et al., 2018) and Mexico 427 (Inomata et al., 2020). Recent advances in deep learning algorithms may even allow to automatize the inventory of archaeological remains (Oliveira et al., 2021; Trier et al., 2021). For instance, 428 429 Oliveira et al. (2021) applied CNNs on ALS data to automatically detect charcoal kilns dating back to the industrial development period (17th-19th century) in North-eastern France. However, 430 remote and automatic detection still requires confirmation, either by field observations or through 431 the experienced eyes of archaeologists and geo-historians who can read and interpret images 432 processed from LiDAR data. 433

In Western Europe, many big woodlands have been continuously mapped or mentioned in 434 435 archives since the Middle Ages, so that they have long been considered as relicts of prehistoric forests (Maury, 1850). This hypothesis was first challenged by the discovery of former Roman 436 settlements in these forests (Cauchemé, 1912; Desbordes, 1973; Laffite et al., 2002) and it is now 437 largely invalidated by ALS data which has revealed that these ancient forests were established on 438 439 former agricultural lands, often intensively cultivated during the Middle Ages and Antiquity (Fig. 6) (Fruchart, 2020; Georges-Leroy et al., 2011; Rassat & Hugonnier, 2017). Figure 6 illustrates this 440 phenomenon by unveiling past land uses hidden below treetops of the Compiègne forest in 441 Northern France, questioning the existence of prehistoric forest remnants in the Gallo-Roman 442 lowlands. With the increasing amount of land covered by ALS data (Fruchart, 2020), it becomes 443 obvious that what we today consider to be very ancient forests can result from recolonization of 444 abandoned Roman farmlands (Georges-Leroy et al., 2011). Also in Eastern Europe, ALS unveiled 445 446 more than 300 km of field boundaries and many (pre-)Roman settlements in the iconic "primary" forest of Bialowieza in Poland, indicating that the present forest has largely established on former 447 448 Celtic, Roman, and medieval fields, towards the 13th century AD (Stereńczak et al., 2020). Beyond the reconstruction of the past landscapes, ALS renders it possible to assess the impact of past land 449 uses on current vegetation patterns and ecosystem processes. For example, buried former Roman 450 451 settlements typically host a species-rich, nitrogen-demanding understory, which often strongly 452 contrasts with the surrounding species-poor, acidophilous forest vegetation (Dambrine et al., 2007; Dupouey et al., 2002; Plue et al., 2008). Interestingly, the soil seed bank in the Compiègne 453 forest indicates that plant communities associated with these former settlements can self-454 perpetuate over time (Plue et al., 2008). This has been related to long-lasting alterations of 455 biogeochemical cycles, which extend far beyond the settlement, thereby creating strong ecological 456 457 gradients with different species assemblages (Dambrine et al., 2007).

458	Airborne LiDAR data also revealed the recurrence of certain human artefacts, even outside ancient
459	settlements located in formerly cultivated land, and highlight their possible ecological significance
460	in forests. We hereafter give three examples. Firstly, in North-eastern France, closed depressions
461	found on calcareous substratum have long been supposed to be of natural origin, but
462	archaeological research has suggested that they were rather artificial excavations from the late
463	Iron Age and Roman times, used to (i) extract marls (i.e., calcium carbonate or lime-rich mud) to
464	amend agricultural lands and/or to (ii) create local depression to collect water for livestock
465	(Etienne et al., 2011). Since this early publication, similar closed depressions have been recorded
466	thanks to ALS data in many "post-Roman" ancient forests elsewhere in Northern France (see Fig. 6
467	for an illustration in the Compiègne forest), suggesting that liming was a common practice during
468	Gallo-Roman times. Long-lasting effects on soil properties, plant communities, tree growth, and
469	forest health are thus expected (Brasseur et al., 2018; Dambrine et al., 2007; Dupouey et al., 2002;
470	Moore & Ouimet, 2021). For instance, the effect of ancient liming practices is still visible on
471	today's soil pH profile of post-agricultural forests, albeit this effect diminishes with the age since
472	afforestation (Brasseur et al., 2018). Being able to date the approximate age of the last agricultural
473	practices before afforestation makes it possible to estimate the magnitude of the imprint left by
474	former agricultural practices in the soil, and thus the effect on forest biodiversity and ecosystem
475	processes. The last agricultural practices are precisely those that most impacted the microrelief
476	preserved under the canopy of post-agricultural forests. Because of these microreliefs' imprints,
477	geo-historians and archaeologists are able to read images from processed ALS data, such as a DTM
478	with hillshade (Fig. 6), and interpret characteristic microreliefs to identify Middle Ages strip fields
479	with cultivation ridges (Fig. 6b), Gallo-Roman linear agrarian fields (Fig. 6c), or even Celtic fields
480	(Meylemans et al., 2015). The approximate age since afforestation as well as the type of former
481	agricultural practices can be key explanatory variables to capture time-lag dynamics in the

response of understory plant communities to the acidification rates of afforested soils that were
formerly cultivated (De Schrijver et al., 2012).

Secondly, another insight from ALS data is the evidence of an incredibly high density of former 484 485 charcoal kilns (i.e., chambers or ovens to turn wood into choarcal) in several forests across Europe, from North-eastern France to Norway (Oliveira et al., 2021; Trier et al., 2021). This not only 486 indicates the huge intensity at which European forests used to be managed from the Middle Ages 487 to the end of the 19th century when humans started to mine and drill fossil fuels (Oliveira et al., 488 489 2021), often as short-rotation coppice woodlands, but also that soils have been considerably enriched in organic matter, carbon, and ash (Bonhage et al., 2020; Rutkiewicz et al., 2019). As a 490 result, these former "charcoal-producing coppices", that are often managed as high forests 491 492 nowadays, harbour different plant communities and soil properties compared to woodlands that have been continuously managed as high forests. For instance, the Bernadouze forest in the 493 494 French Pyrenees was initially managed as a beech coppice with fir standard before being progressively transformed, during the 15th-17th century, into a monospecific beech coppice for 495 charcoal production, inducing long lasting effects on today's biodiversity and soli processes 496 497 (Fouédjeu et al., 2021). Charcoal-producing coppices may contain an additional 4.9 to 8.9 Mg ha⁻¹ of soil carbon, and even more (Bonhage et al., 2020). In regions where former charcoal kilns were 498 associated with metal furnaces to forge weapons during medieval times, it may further explain 499 500 local soil pollution and its persisting effect on biodiversity and ecosystem processes (Karlsson et al., 2015). 501

502 Thirdly, still in the Compiègne forest, ALS data also unveiled a number of raised, circular structures 503 that concentrated along a curved line into the forest, a few hundreds of meters from the current 504 edge. Field surveys identified them as rabbit warrens, that are artificial earth clods, also called 505 "mottes à conils" in French, erected at the end of the Middle Ages to rear rabbits for royal hunting

506	parties (Germond et al., 1988; Williamson, 2008; Zadora-Rio, 1986). This finding allows not only to
507	date the introduction of rabbit in Northern France somewhere between the 12th and 13th
508	century, and hence determine when forest dynamics started to be influenced by this invasive
509	rodent species, but also to locate the forest edge at that time (Fig. 6). It is therefore possible to
510	distinguish between the medieval forest and the modern one, providing an explanation for
511	differences of soil and vegetation characteristics.
512	In sum, LiDAR data not only prompted an "archaeological revolution" by revealing unexpected
513	past human activities and their intensity, but also play a crucial role to unravel the effects of these
514	(pre)historical activities on current biodiversity and ecosystem functioning. More than ever,
515	present ecosystems and landscapes must be viewed as a legacy of past interactions between
516	humans and their environment.

517 Perspectives

Although we focused our review on the lagging dynamics of vegetation changes in the understory 518 of European temperate forests, we suggest that the exact same suite of LiDAR-derived variables 519 520 can also be used to study time-lag dynamics in the response of other taxonomic groups to macroenvironmental changes. Indeed, plants in the understory layer provide food resources and 521 microhabitats (i.e., microclimatic conditions) for other organisms living in, on, or near the soil 522 surface. Therefore, time lags in vegetation changes can perpetuate and generate a domino effect 523 524 on other taxa and interaction networks throughout complex aboveground-belowground linkages (Bardgett & Wardle, 2010). Such cascading effects not only involve bottom-up chain reactions 525 across trophic levels (e.g., from primary producers to primary consumers or soil decomposers) 526 527 (Valencia et al., 2018) but also top-down chain reactions. Indeed, changes in herbivore density or composition (e.g., ungulates or insects), sometimes driven by macroclimate warming and 528 529 disrupted plant-herbivore interactions (Rasmann et al., 2014; Vitasse et al., 2021), can have longterm biological legacies on aboveground plant community composition (Hamann et al., 2021; 530 Nuttle et al., 2014). For instance, Nuttle et al. (2014) showed that the initial density in white-tailed 531 deer (Odocoileus virginianus) in Pennsylvania still influences current understory vegetation in 30-532 year-old, closed-canopy forests. In the meantime, LiDAR-derived variables have been successfully 533 incorporated as predictor variables into models of species diversity and distribution across a wide 534 535 range of taxonomic groups (de Vries et al., 2021; Farrell et al., 2013; Hattab et al., 2017; Moeslund et al., 2019; Simonson et al., 2014), often as a mean to capture local processes such as 536 microclimates and biotic interactions (Lembrechts et al., 2019; Zellweger et al., 2019). Hence, 537 LiDAR-derived variables have the potential to significantly improve species distribution modelling 538 across a wide range of taxa, inform us on the structure of trophic webs, and therefore help us 539 better understand time-lag dynamics perpetuating across trophic levels. 540

541	Remote sensing science continues to innovate and thus some research perspectives should be
542	highlighted here. Innovations can come either from the LiDAR sensor itself, the combination with
543	other sensors (e.g., coupling LiDAR data with hyperspectral images) or from other technologies.
544	Typical LiDAR data retrieve discrete echoes in only one wavelength. Today, the two big new
545	innovations in LiDAR technology are (1) the analysis on the full-waveform laser information and (2)
546	the use of multispectral lasers, which bring both high resolution 3D point clouds and classical
547	multispectral information. The first one allows much more precise information of surfaces than
548	typical multi-echo LiDAR, especially for forest structure and composition (Fassnacht et al., 2016;
549	Koenig & Höfle, 2016). The second allows the remote identification of tree species (Amiri et al.,
550	2019) as well as the production of typical remote sensing indicators, such as normalized difference
551	vegetation index (NDVI), for understory conditions not easily accessible with classical multispectral
552	images that do not penetrate forest canopy cover. Additionally, data fusion remains one of the
553	main interests in remote sensing technology. For example, hyperspectral data has proven its
554	complementarity with LiDAR data to better understand ecosystem functioning (Ewald et al., 2018).
555	While LiDAR data gives precise information about the 3D structure of surfaces, hyperspectral
556	images give more precise information of surface reflectance (hundreds of spectral bands) than
557	classical multispectral images. Hyperspectral data is thus more relevant than LiDAR data to provide
558	information on stand composition and can help detect foliar traits and leaf chemical composition
559	(Ewald et al., 2018). For instance, in terms of lagging dynamics involving past land uses,
560	hyperspectral data could be used to locate particular pollutants in the upper canopy layer (for
561	example perchlorates that affect photosynthesis and thus surface reflectance) as an indirect
562	indicator of pollutant concentration in the soil (Wang et al., 2018) likely affecting plant species
563	composition in the understory. Coupling LiDAR and hyperspectral data could therefore be of high
564	interest and could give precious information of time-lag dynamics in biodiversity changes.
565	Additionally, it is possible to combine LiDAR data from a single survey with other types of

26 Journal of Ecology: Confidential Review copy 566 technologies to monitor changes in forest structure over time and thus better understand time-lag 567 dynamics in the forest understory. For example, photogrammetry can retrieve 3D surfaces to 568 generate digital surface models (DSMs) at different time periods using time series of RGB images. Such time series of DSMs derived from photogrammetry could then be coupled with a single 569 LiDAR-derived DTM to monitor changes in maximum canopy height over time (Michez et al., 570 571 2016). Pleiades satellites are interesting in this regard as they allow to produce DSMs across large spatial extents at a relatively low price. In line with Pleiades, the CO3D mission is a pioneer 572 mission, planned to be launched by the CNES (the French Spatial Agency) in mid-2023. Ultimately, 573 the CO3D mission will provide a worldwide high (1-m) resolution DSM in 2025. Combining past 574 photogrammetric data sets, where available, with more recent time series of DSMs, from either 575 576 airborne or spaceborne data, would also allow obtaining the longer-term data necessary to observe temporal dynamics. 577

578 Finally, there are exiting recent advances and open-source tools to overcome challenges associated with LiDAR data handling and processing (Atkins et al., 2022). First, recent packages 579 developed for the R statistical software (R Core Team, 2021), such as the lidR (Roussel et al., 2020) 580 581 and forestr package (Atkins et al., 2018) for ALS and TLS data, respectively, have greatly advanced 582 the handling and processing of LiDAR data. Second, it is now possible to call programming languages such as Python, which is chiefly used by the remote sensing community, directly within 583 584 the R environment, thanks to the reticulate package (Ushey et al., 2021). It is also possible and quite usual to wrap C/C++ functions within R. Using a compiled language allows a speedier 585 execution when processing huge point cloud data sets. This, will allow ecologists – that are often 586 587 most familiar with R – to better access the recent open-source tools developed and used by the remote sensing community. Third, recent advances in R and Python to use machine learning and 588 deep learning algorithms (e.g., the keras Python library) (Kalinowski et al., 2021) will help to lift 589 technical barriers in linking LiDAR data with ecological data from field observations. Finally, data 590

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- 591 processing facilities continue to develop steadily, with increased access to data and computer
- 592 centres.

593 Conclusion

To conclude, LiDAR data can unveil past forest management interventions and even past land uses 594 within temperate deciduous forests. LiDAR technology has the capacity to monitor and determine 595 596 fine-grained structural information – namely: the vertical complexity of vegetation layering and the micro-topographic variations at the ground surface – invisible to the naked eye, providing far 597 more information than conventional field surveys. Yet, LiDAR data alone is insufficient and still 598 requires to be coupled with field surveys to calibrate models, validate predictions, and correct 599 600 misclassifications of items. Besides, LiDAR technology needs a highly diverse set of expertise to unveil any useful information hidden in the data. Hence, LiDAR is a transdisciplinary tool for plant, 601 soil, and historical ecologists as well as for foresters, archaeologists, and remote sensing scientists 602 603 to work together and help each other advance their respective fields of research. With this in mind, we encourage plant and soil ecologists to work with historians, archaeologists, and remote 604 605 sensing scientists in order to use meaningful LiDAR-derived variables, such as the ones we featured in this review (Figs. 3-6), as surrogates to capture time-lag dynamics in biotic responses 606 to long-term macro-environmental changes. Doing so will ultimately help us better predict the 607 current and future distribution of forest biodiversity. 608

609 *"Inside every sane person there's a madman struggling to get out," said the shopkeeper. "That's*610 *what I've always thought. No one goes mad quicker than a totally sane person."* –Terry Pratchett,
611 The Light Fantastic (1986)

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622 **Conflict of interest**

623 No conflict of interest to declare.

624 Authors' contributions

JL conceptualized the project, designed the review paper, wrote the introduction and conclusion 625 sections, and led the writing. FZ and JJL co-led the writing of section 1 on using LiDAR to unveil 626 past forest management practices with contributions from PDF, KVM, CM, RM, EVG, and DR. HH 627 led the writing of section 2 on using LiDAR data to highlight soil compaction from skid trails with 628 contributions from BB and GD. GD led the writing of section 3 on using LiDAR data to unveil past 629 land uses with contributions from BB and JB. ML led the writing of section 4 on the perspectives 630 631 with contribution from RM. SD, led the writing of Boxes 1 and 2 with contributions from SA and KD. EVG designed Fig. 1 with contribution from JL. SD designed Figs. 2 and 3 with contribution 632 from JL. CM designed Fig. 4 with contribution from JL. EGM designed Fig. 5 with contribution from 633 634 HH and JL. EGM & BB designed Fig.6 with contribution from JL. All authors significantly revised the manuscript and approved it for submission. 635

636 Data availability

637 No data was used in this essay review.

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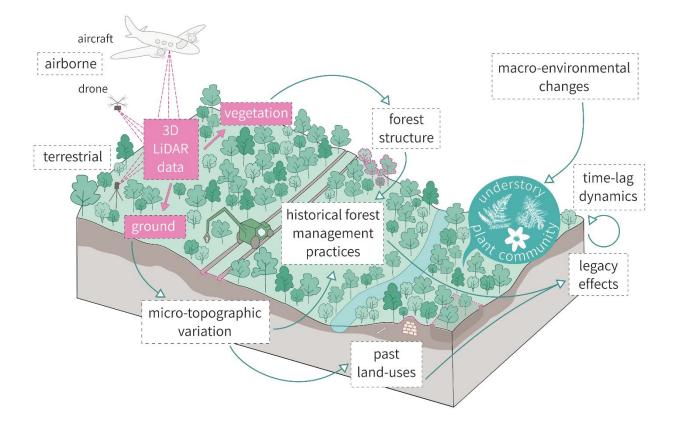


Fig. 1: Conceptual figure illustrating how light detection and ranging (LiDAR) data can be used to 1118 assess micro-topographic variation (e.g., skid trails) and forest structure (e.g., vertical layering of 1119 vegetation) at a landscape level, and thus highlight legacy effects still affecting the current 1120 1121 composition of understory plant communities and their responses to macro-environmental changes through time-lag dynamics. For instance, using well-chosen LiDAR-derived variables (see 1122 1123 the main text and subsequent figures), it is possible to not only capture the imprints of historical forest management practices (e.g., ancient coppice-with-standards converted to high forests after 1124 World War II or the more recent intensification of heavy vehicles' traffic to harvest timber) but 1125 1126 also to unveil past land uses (e.g., ancient settlements or agricultural fields).

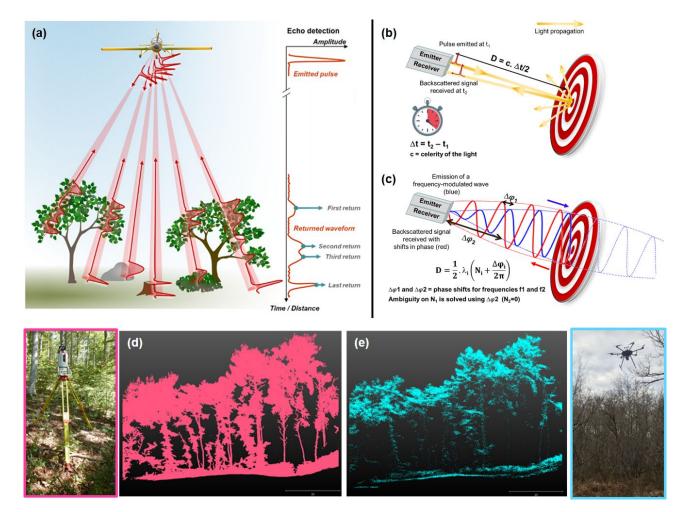


Fig. 2: How light detection and ranging (LiDAR) works (a, b, c) and the mean to acquire LiDAR data
from below or from above treetops (d, e). Upper-left panel (a): example of a non-stationary
airborne LiDAR system (ALS) on board an aircraft. Upper-right panels (b, c): basic principles of
time-of-flight vs. phase-shift LiDAR. Lower panels (d, e): data visualization of raw LiDAR point
clouds extracted from both a stationary terrestrial LiDAR system (TLS) (Riegl VZ400) and a nonstationary ALS (YellowScan Vx20) covering the exact same study area in the Aigoual forest
(France).

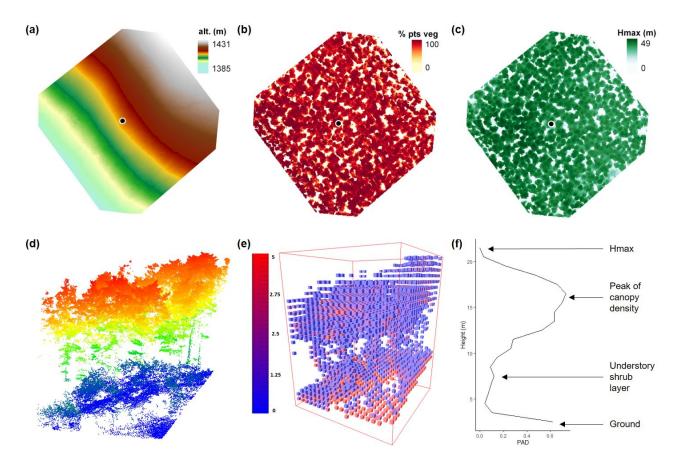
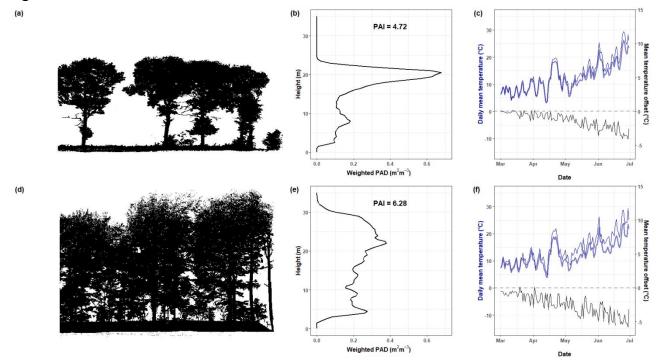
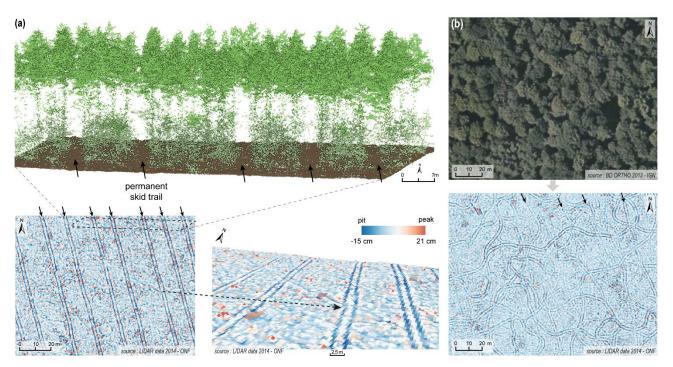


Fig. 3: Examples of LiDAR-derived variables to assess the vertical complexity below treetops. 1136 1137 Upper panels (a, b, c): raster layers, at 50 cm × 50 cm resolution, showing the digital terrain model 1138 (DTM) (a), the percentage of points classified as "vegetation" (a proxy for canopy density) (b), and maximum canopy height (Hmax) (c) across a 0.5 ha area (ca. 70 m × 70 m) in the Aigoual forest 1139 1140 (France). Lower panels (d, e, f): close-up on the raw 3D LiDAR point cloud across an area of 20 m × 1141 20 m size (d) to derive plant or leaf area density (PAD or LAD) computed for small volume units or voxels of 50 cm × 50 cm × 50 cm size (e) further aggregated by height layer to generate a 1142 1143 vegetation profile of PAD values (f). Data were acquired with a non-stationary ALS (YellowScan 1144 Vx20) (cf. Fig. 2e).



1146 Fig. 4: Using terrestrial LiDAR systems (TLS) to derive variables explaining the variation in forest microclimates in an open (a, b, c) vs. dense (d, e, f) oak forest located in Belgium. Left panels (a, d): 1147 cross section of the raw lidar point cloud data. Central panels (b, e): vertical profiles of plant area 1148 1149 density (PAD) $(m^2 m^{-3})$ values as a function of the height of the same point clouds used to compute the total plant area index (PAI), which is the integral of the PAVD-profile over the canopy 1150 height. Right panels (c, f): daily mean temperature (°C, blue lines) collected both inside (light-blue 1151 1152 lines) and outside (dark-blue lines) the respective forest stands. The daily mean temperature 1153 offset, determined as the temperature inside the forest minus the temperature outside the forest, is shown in black as well. The LiDAR data was acquired using a RIEGL VZ400 (RIEGL Laser 1154 1155 Measurement Systems GmbH, Horn, Austria). Single-scan position TLS was carried out in a dense and open forest in Belgium during the summer of 2018. 1156



1158 Fig. 5: Using airborne LiDAR systems (ALS) to unveil regular (a) and irregular (b) skid trails below 1159 treetops. A local relief model (LRM), at 50 cm resolution, was derived from the digital terrain 1160 model (DTM) of the Compiègne forest in Northern France. Left panel (a): a 3D view of the raw LiDAR point cloud with regular skid trails, illuminated in dark blue colors by the LRM, below the 1161 1162 canopy cover of a young forest stand. Right panel (b): irregular and meandering patterns of skid trails, likely from different ages, below the canopy cover of a more mature forest stand. Green and 1163 1164 brown points represent points classified as vegetation and soil, respectively. Bluish and reddish 1165 colours in the LRM refer to the micro-variation of the terrain microrelief and represent hollows (ruts here) and bumps, respectively. The LiDAR data was acquired by the Office National des 1166 Forêts (ONF) across the entire lowland forest of Compiègne (144 km²). The AERODATA Company 1167 1168 used a Riegl LMS-680i LiDAR installed on-board an aircraft and performed flights in February 2014 to get an average density of 12 points per m². 1169

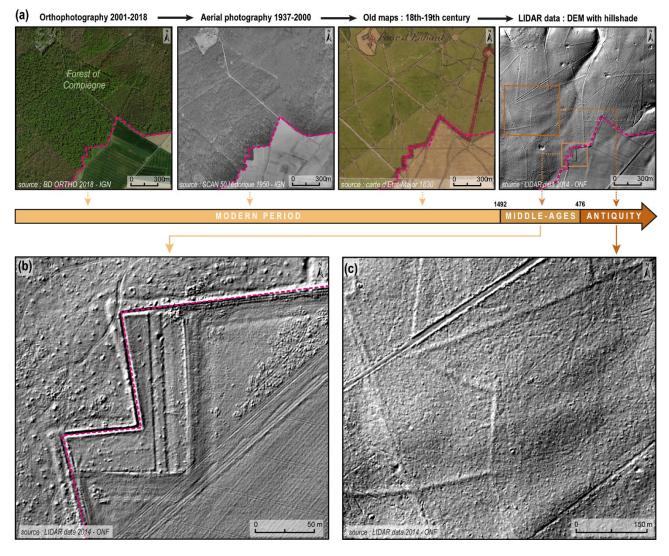
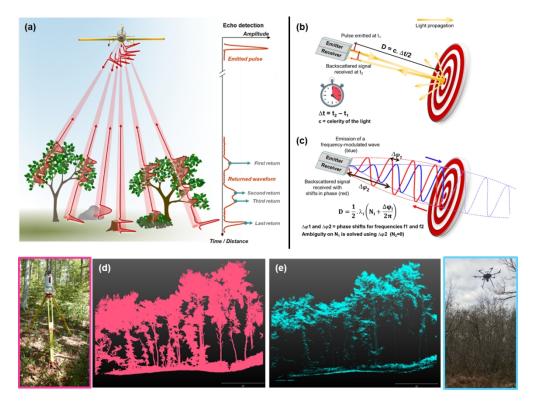


Fig. 6: Using airborne LiDAR systems (ALS) to extend a chronosequence (a) and unveil past land 1171 uses (b, c). Upper panel (a): chronosequence of land uses at the southern edge of the Compiègne 1172 1173 forest in Northern France reconstructed with the help of modern orthophotography, historical 1174 aerial photography, old archives from Cassini maps, and LiDAR data allowing us to extend the chronosequence until the Middle Ages and Antiquity. We used a digital terrain model (DTM), at 50 1175 1176 cm resolution, with hillshade to unveil former agricultural practices inside the study area. The DEM with hillshade on the right-hand side of panel (a) clearly highlights artificial excavations (i.e., see 1177 the closed depressions) likely originating from the late Iron Age and Roman times and suggesting 1178 1179 marling/liming practices to enrich agricultural fields. Bottom panels (b, c): close-up across two sites near the southern edge of the forest: evidence of (b) a typical late Middle Ages strip field 1180

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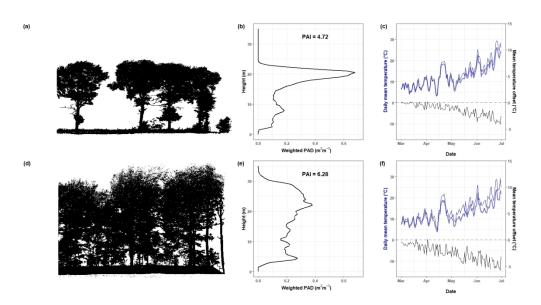
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- 1181 with cultivation ridges and (c) linear microreliefs corresponding to a network of Gallo-Roman
- agrarian fields and secondary roads. The LiDAR data was acquired by the Office National des
- 1183 Forêts (ONF) across the entire lowland forest of Compiègne (144 km²). The AERODATA Company
- used a Riegl LMS-680i LiDAR installed on-board an aircraft and performed flights in February 2014
- 1185 to get an average density of 12 points per m².



How light detection and ranging (LiDAR) works (a, b, c) and the mean to acquire LiDAR data from below or from above treetops (d, e). Upper-left panel (a): example of a non-stationary airborne LiDAR system (ALS) on board an aircraft. Upper-right panels (b, c): basic principles of time-of-flight vs. phase-shift LiDAR. Lower panels (d, e): data visualization of raw LiDAR point clouds extracted from both a stationary terrestrial LiDAR system (TLS) (Riegl VZ400) and a non-stationary ALS (YellowScan Vx20) covering the exact same study area in the Aigoual forest (France)

570x425mm (59 x 59 DPI)



Using terrestrial LiDAR systems (TLS) to derive variables explaining the variation in forest microclimates in an open (a, b, c) vs. dense (d, e, f) oak forest located in Belgium. Left panels (a, d): cross section of the raw lidar point cloud data. Central panels (b, e): vertical profiles of plant area density (PAD) (m2 m–3) values as a function of the height of the same point clouds used to compute the total plant area index (PAI), which is the integral of the PAVD-profile over the canopy height. Right panels (c, f): daily mean temperature (°C, blue lines) collected both inside (light-blue lines) and outside (dark-blue lines) the respective forest stands. The daily mean temperature offset, determined as the temperature inside the forest minus the temperature outside the forest, is shown in black as well. The LiDAR data was acquired using a RIEGL VZ400 (RIEGL Laser Measurement Systems GmbH, Horn, Austria). Single-scan position TLS was carried out in a dense and open forest in Belgium during the summer of 2018

924x507mm (47 x 47 DPI)